ECEN 314: Signals and Systems

Lecture Notes 3: Basic System Properties

Reading:

- Current: SSOW 1.5-1.6
- Next: SSOW 2.1

1 Causality

A system is *causal* if the output does not anticipate future values of the input, i.e., if the output at any time depends only on values of the input up to that time.

- All real-time physical systems are causal, because time only moves forward. Effect occurs after cause. (Imagine if you own a non-causal system whose output depends on tomorrows stock price.)
- Causality does not apply to spatially varying signals. (We can move both left and right, up and down.)
- Causality does not apply to systems processing recorded data.

Example (Causal or non-causal):

•
$$y(t) = x^2(t-1)$$

- y(t) = x(t+1)
- y[n] = x[-n]
- $y[n] = 2^{n+1}x^3[n-1]$

Mathematically (in CT), consider a system $x(t) \to y(t)$. Let $x_1(t)$ and $x_2(t)$ be two input signals with corresponding output signals $y_1(t)$ and $y_2(t)$, respectively. Then, the system is causal if and only if

$$x_1(t) = x_2(t), \quad \forall t < t_0 \implies y_1(t) = y_2(t), \quad \forall t < t_0$$

2 Time-invariance

Informally, a system is time-invariant (TI) if its behavior does not depend on what time it is. Mathematically (in CT), a system $x(t) \rightarrow y(t)$ is TI if

$$x(t) \to y(t) \implies x(t-t_0) \to y(t-t_0), \quad \forall t_0 \in \mathbb{R}$$

Example (TI or time-varying (TV)):

- $y(t) = x^2(t-1)$. To check whether this system is TI or TV, we need to determine the output corresponding to the input $x(t-t_0)$ and then compare it with $y(t-t_0)$. Let $x'(t) = x(t-t_0)$. Then $y'(t) = [x'(t-1)]^2 = [x(t-1-t_0)]^2$. On the other hand, $y(t-t_0) = x^2(t-t_0-1)$. We conclude that $y'(t) = y(t-t_0)$ so the system is TI.
- $y[n] = 2^{n+1}x^3[n-1]$. Let $x'[n] = x[n-n_0]$. Then, $y'[n] = 2^{n+1}(x'[n-1])^3 = 2^{n+1}(x[n-n_0-1])^3$. On the other hand, $y[n-n_0] = 2^{n-n_0+1}x^3[n-n_0-1]$. In general, $y'[n] \neq y[n-n_0]$, so the system is TV.
- y[n] = x[-n]. Let $x'[n] = x[n n_0]$. Then, $y'[n] = x'[-n] = x[-n n_0]$. On the other hand, $y[n n_0] = x[-(n n_0)] = x[-n + n_0]$. In general, $y'[n] \neq y[n n_0]$, so the system is TV.

Fact: If the input to a TI system is periodic with a period T, then the output is also periodic with a period T.

Proof. Suppose x(t+T) = x(t) for all $t \in \mathbb{R}$ and $x(t) \to y(t)$. Then, by TI, $x(t+T) \to y(t+T)$. The output of a system is fully determined by the input, so y(t) = y(t+T), i.e., the output is also periodic with the same period T.

3 Linearity

A (CT) system is *linear* if it satisfies the following property:

 $x_1(t) \to y_1(t)$ and $x_2(t) \to y_2(t) \implies ax_1(t) + bx_2(t) \to ay_1(t) + by_2(t), \quad \forall a, b \in \mathbb{C}$

Properties: Let $x(t) \to y(t)$ be a linear CT system. Then,

• (Additivity)

$$x_1(t) \rightarrow y_1(t)$$
 and $x_2(t) \rightarrow y_2(t) \implies x_1(t) + x_2(t) \rightarrow y_1(t) + y_2(t)$

• (Homogeneity)

$$x_1(t) \to y_1(t) \implies ax_1(t) \to ay_1(t), \quad \forall a \in \mathbb{C}$$

• (Superposition)

$$x_k(t) \to y_k(t) \implies \sum_k a_k x_k(t) \to \sum_k a_k y_k(t), \quad \forall a_k \in \mathbb{C}$$

Example (Linear or nonlinear):

- y(t) = x(2t). Let $y_1(t) = x_1(2t)$, $y_2(t) = x_2(2t)$, and $x'(t) = ax_1(t) + bx_2(t)$. Then $y'(t) = x'(2t) = ax_1(2t) + bx_2(2t) = ay_1(t) + by_2(t)$. Conclusion: Linear.
- $y[n] = x^2[n]$. Let $y[n] = x^2[n]$ and x'[n] = 2x[n]. Then $y'[n] = (x'[n])^2 = (2x[n])^2 = 4x^2[n] \neq 2y[n]$. Conclusion: The system is not additive and hence is nonlinear.

Facts:

- a) A system is linear if and only if it is both additive and homogeneous.
- b) For linear systems, zero input \longrightarrow zero output.
- c) A linear system is causal if and only if it satisfies the condition of initial rest:

$$x(t) = 0, \quad \forall t < t_0 \implies y(t) = 0, \quad \forall t < t_0$$

Proof. Part a): We only need to prove the "if" part. Suppose that the system $x(t) \to y(t)$ is both additive and homogeneous and that $x_1(t) \to y_1(t)$, $x_2(t) \to y_2(t)$. By homogeneity, $ax_1(t) \to ay_1(t)$ and $bx_2(t) \to by_2(t)$. Furthermore, by additivity, $ax_1(t) + bx_2(t) \to ay_1(t) + by_2(t)$. Conclusion: The system is linear.

Part b): Let $x(t) \to y(t)$ be a linear system. By homogeneity, $0 \cdot x(t) \to 0 \cdot y(t)$. Conclusion: Zero input \longrightarrow zero output.

Part c): Let $x(t) \to y(t)$ be a linear system. Let x(t) = 0 for all $t < t_0$ and let x'(t) = 0be a zero input. From part b), y'(t) = 0 is a zero output. Note that x(t) = x'(t) for all $t < t_0$. If the system is also causal, then y(t) = y'(t) = 0 for all $t < t_0$. That is, the initial rest condition must be satisfied. Conversely, suppose that the initial rest condition is satisfied. Let x(t) = x'(t) for all $t < t_0$. Then, x(t) - x'(t) = 0 for all $t < t_0$. By linearity, $x(t) - x'(t) \to y(t) - y'(t)$. Furthermore, by the initial rest condition, the output y(t) - y'(t) = 0 for all $t < t_0$. Thus, we have y(t) = y'(t) for all $t < t_0$, and we conclude that the system must be causal.

Exercise: A DT system F is known to be TI. Three test input-output signal pairs are depicted below (all signals are zero outside the region shown).

- (a) Could the system be causal?
- (b) Determine the response of the system to the unit impulse input.
- (c) Could the system be linear?

