

EXIT Charts and the EXIT Area Theorem

Supplemental Material for Advanced Channel Coding

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1 Introduction

EXtrinsic Information Transfer (EXIT) charts were introduced by ten Brink in 1999 as a useful tool to understand the convergence of Turbo decoding for different component codes [1]. His work led to the EXIT area theorem and this was put on rigorous mathematical footing by Ashikhmin, Kramer, and ten Brink in 2004 [2]. A little later, Measson et al. showed that the area theorem also allows one to upper bound the MAP decoding threshold using information gleaned from iterative decoding [3]. Together these ideas highlight the fundamental connections between iterative information processing and optimal information processing.

2 EXIT Functions

Let \mathcal{C} be a length- n binary code and assume that a random codeword $\underline{X} = (X_1, \dots, X_n)$ is chosen according to $P_{\underline{X}}(\underline{x})$. Suppose $Y_i \in \{0, 1, ?\}$ is an observation of X_i through a BEC with erasure probability ϵ_i and $\underline{Y} = (Y_1, \dots, Y_n)$ is the channel output vector. The notation $\underline{Y}_{\sim i}$ will be used to denote the vector $(Y_1, \dots, Y_{i-1}, Y_{i+1}, \dots, Y_n)$ and the notation $\underline{Y}(\underline{\epsilon}) = (Y_1(\epsilon_1), \dots, Y_n(\epsilon_n))$ will be used to emphasize the dependence on $\underline{\epsilon} = (\epsilon_1, \dots, \epsilon_n)$.

Definition 1. The **EXIT function for the i -th bit** of \mathcal{C} is defined to be

$$h_i(\underline{\epsilon}) \triangleq H(X_i | \underline{Y}_{\sim i}(\underline{\epsilon}_{\sim i})).$$

If all $\epsilon_i = \epsilon$ for $i \in [n]$, then the simplified notation $h_i(\epsilon) \triangleq h_i((\epsilon, \dots, \epsilon)) = H(X_i | \underline{Y}_{\sim i}(\epsilon))$ is used. Similarly, the **average EXIT function** of \mathcal{C} is defined to be $h(\underline{\epsilon}) = \frac{1}{n} \sum_{i=1}^n h_i(\underline{\epsilon})$ in the first case and $h(\epsilon) = \frac{1}{n} \sum_{i=1}^n h_i(\epsilon)$ in the second.

Lemma 2. Using the above setup, the EXIT function for the i -th bit of \mathcal{C} satisfies

$$h_i(\underline{\epsilon}) = \frac{d}{d\epsilon_i} H(\underline{X} | \underline{Y}(\underline{\epsilon})).$$

Proof. Suppressing the explicit dependence on $\underline{\epsilon}$, this follows from

$$\begin{aligned} \frac{d}{d\epsilon_i} H(\underline{X} | \underline{Y}) &= \frac{d}{d\epsilon_i} [H(X_i | \underline{Y}) + H(\underline{X}_{\sim i} | X_i, \underline{Y})] && (H \text{ chain rule}) \\ &= \frac{d}{d\epsilon_i} H(X_i | \underline{Y}) + \frac{d}{d\epsilon_i} \underbrace{H(\underline{X}_{\sim i} | X_i, \underline{Y}_{\sim i})}_{\text{ind. of } \epsilon_i} && (\underline{X}_{\sim i} \rightarrow X_i \rightarrow Y_i \text{ Markov chain}) \\ &= \frac{d}{d\epsilon_i} \left[\mathbb{P}(Y_i = ?) H(X_i | \underline{Y}, Y_i = ?) + \mathbb{P}(Y_i \neq ?) \underbrace{H(X_i | \underline{Y}, Y_i \neq ?)}_{Y_i \neq ? \Rightarrow Y_i = X_i \Rightarrow H=0} \right] && (\text{Average over } Y_i) \\ &= \frac{d}{d\epsilon_i} \epsilon_i H(X_i | \underline{Y}_{\sim i}) = H(X_i | \underline{Y}_{\sim i}). && (\mathbb{P}(Y_i = ?) = \epsilon_i) \end{aligned}$$

□

Lemma 3. Using the above setup, let $H(\underline{X}|\underline{Y}(\underline{\epsilon}(t)))$ denote the conditional entropy evaluated along the BEC path $\underline{\epsilon}(t) = (\epsilon_1(t), \dots, \epsilon_n(t))$ for $t \in [0, 1]$. Then,

$$H(\underline{X}|\underline{Y}(\underline{\epsilon}(1))) - H(\underline{X}|\underline{Y}(\underline{\epsilon}(0))) = \int_0^1 \underline{h}(\underline{\epsilon}(t)) \cdot \underline{\epsilon}'(t) dt = \int_0^1 \left(\sum_{i=1}^n h_i(\underline{\epsilon}(t)) \epsilon_i'(t) \right) dt,$$

where $\underline{h}(\underline{\epsilon}) = (h_1(\underline{\epsilon}), \dots, h_n(\underline{\epsilon}))$. If the BEC path satisfies $\epsilon_i(t) = \epsilon(t)$ for $i \in [n]$, then we find that

$$H(\underline{X}|\underline{Y}(\epsilon(1))) - H(\underline{X}|\underline{Y}(\epsilon(0))) = \int_0^1 \left(\sum_{i=1}^n h_i(\epsilon(t)) \epsilon'(t) \right) dt = n \int_0^1 h(\epsilon(t)) \epsilon'(t) dt.$$

Proof. These results follow directly from Lemma 2 and vector calculus. \square

Example 4. Consider the non-linear code $\mathcal{C} = \{00, 10, 11\}$ where codewords are chosen, respectively, with probabilities $\frac{1}{2}, \frac{1}{4}, \frac{1}{4}$. In this case, $H(\underline{X}) = \frac{3}{2}$ and it is easy to verify that

$$H(X_1|Y_2(\epsilon_2)) = \epsilon_2 + \frac{3}{4}(1 - \epsilon_2)h\left(\frac{1}{3}\right)$$

$$H(X_2|Y_1(\epsilon_1)) = \epsilon_1 h\left(\frac{1}{4}\right) + \frac{1}{2}(1 - \epsilon_1),$$

where $h(x) = x \log_2 \frac{1}{x} + (1 - x) \log_2 \frac{1}{1-x}$ is the binary entropy function. Integrating gives

$$\begin{aligned} \int_0^1 [H(X_1|Y_2(\epsilon)) + H(X_2|Y_1(\epsilon_1))] d\epsilon &= \int_0^1 \left[\epsilon + \frac{3}{4}(1 - \epsilon)h\left(\frac{1}{3}\right) + \epsilon h\left(\frac{1}{4}\right) + \frac{1}{2}(1 - \epsilon) \right] d\epsilon \\ &= \left(\frac{1}{2} + \frac{1}{4} \right) + \left(\frac{3}{8}h\left(\frac{1}{3}\right) + \frac{1}{2}h\left(\frac{1}{4}\right) \right) \\ &= \frac{3}{4} + \frac{3}{4} = \frac{3}{2}. \end{aligned}$$

One can also verify, either directly or via differentiation, that

$$H(\underline{X}|\underline{Y}(\underline{\epsilon})) = \epsilon_1 \epsilon_2 \frac{3}{2} + \frac{1}{2}(1 - \epsilon_1)\epsilon_2 + \frac{3}{4}\epsilon_1(1 - \epsilon_2)h\left(\frac{1}{3}\right).$$

2.1 Uniform Codeword Distribution

Now, let \mathcal{C} be an (n, k) binary linear code with generator matrix G and parity-check matrix H . Assume that a random codeword \underline{X} is chosen uniformly and transmitted through BECs with output $\underline{Y} \in \{0, 1, ?\}^n$. Let $\mathcal{E}(\underline{y}) \triangleq \{i \in [n] \mid y_i = ?\}$ be set of indices where an erasure occurs. For a set $\mathcal{E} = (e_1, e_2, \dots, e_{|\mathcal{E}|})$ with $e_1 < e_2 < \dots < e_{|\mathcal{E}|}$ and an $m \times n$ matrix $A = (\underline{a}_1, \underline{a}_2, \dots, \underline{a}_n)$ whose i -th column is \underline{a}_i , we let $A_{\mathcal{E}} = (\underline{a}_{e_1}, \underline{a}_{e_2}, \dots, \underline{a}_{e_{|\mathcal{E}|}})$. The same rule can be applied to row vectors by choosing $m = 1$.

Using this notation, the a posteriori probability (APP) distribution for \underline{X} given \underline{Y} is

$$P_{\underline{X}}(\underline{x}|\underline{y}) = \begin{cases} \frac{1}{|V(\underline{y})|} & \text{if } \underline{x} \in V(\underline{y}) \\ 0 & \text{otherwise,} \end{cases}$$

where $V(\underline{y}) = \left\{ \underline{z} \in \mathcal{C} \mid \underline{z}_{\mathcal{E}^c}(\underline{y}) = \underline{y}_{\mathcal{E}^c}(\underline{y}) \right\}$ is set of codewords that are compatible with the observations. Since \mathcal{C} is linear, the set $V(\underline{y})$ is the affine subspace of $\underline{x} \in \{0, 1\}^n$ satisfying

$$H_{\mathcal{E}} \underline{x}_{\mathcal{E}}^T = H_{\mathcal{E}^c} \underline{y}_{\mathcal{E}^c}^T,$$

where $\mathcal{E}(\underline{y})$ is denoted by \mathcal{E} for simplicity and $\underline{y}_{\mathcal{E}^c}$ is a binary vector known by the decoder. Thus, dimension of the solution space is given by $|\mathcal{E}| - \text{rank}(H_{\mathcal{E}})$. Similarly, affine subspace of input vectors $\underline{u} \in \{0, 1\}^k$ compatible with \underline{y} is defined by

$$\underline{u}G_{\mathcal{E}^c} = \underline{y}_{\mathcal{E}^c}$$

and dimension of the solution space is $k - \text{rank}(G_{\mathcal{E}^c})$. Of course, the two spaces must have the same dimension and this implies that

$$k - \text{rank}(G_{\mathcal{E}^c}) = |\mathcal{E}| - \text{rank}(H_{\mathcal{E}}).$$

Since the input distribution is uniform over \mathcal{C} , then these unknown dimensions have full entropy and

$$H(\underline{X}|\underline{Y} = \underline{y}) = |\mathcal{E}| - \text{rank}(H_{\mathcal{E}}) = k - \text{rank}(G_{\mathcal{E}^c}).$$

Lemma 5. *Using the above setup, the conditional entropy $H(\underline{X}|\underline{Y}(\underline{\epsilon}))$ is given by*

$$\begin{aligned} H(\underline{X}|\underline{Y}(\underline{\epsilon})) &= k - \sum_{\mathcal{E} \subseteq [n]} \left(\prod_{i \in \mathcal{E}} \epsilon_i \right) \left(\prod_{i \in \mathcal{E}^c} (1 - \epsilon_i) \right) \text{rank}(G_{\mathcal{E}^c}) \\ &= \sum_{i=1}^n \epsilon_i - \sum_{\mathcal{E} \subseteq [n]} \left(\prod_{i \in \mathcal{E}} \epsilon_i \right) \left(\prod_{i \in \mathcal{E}^c} (1 - \epsilon_i) \right) \text{rank}(H_{\mathcal{E}}). \end{aligned}$$

Let $H^\perp(\underline{X}|\underline{Y}(\underline{\epsilon}))$ denote the conditional entropy when \underline{X} is chosen uniformly from the dual code \mathcal{C}^\perp . Then,

$$H^\perp(\underline{X}|\underline{Y}(\underline{\epsilon})) = H(\underline{X}|\underline{Y}(\underline{1} - \underline{\epsilon})) - k + \sum_{i=1}^n \epsilon_i$$

and computing the derivative with respect to ϵ_i shows that

$$h_i^\perp(\underline{\epsilon}) = 1 - h_i(\underline{1} - \underline{\epsilon}).$$

Proof. The first formula follows from averaging $H(\underline{X}|\underline{Y} = \underline{y}) = k - \text{rank}(G_{\mathcal{E}^c})$ over all all possible erasure patterns because the formula depends only on the erasure pattern and not on the unerased values. The second formula follows from averaging $H(\underline{X}|\underline{Y} = \underline{y}) = |\mathcal{E}| - \text{rank}(H_{\mathcal{E}})$ over all all possible erasure patterns. In this case, the expectation of $|\mathcal{E}|$ is computed using

$$\begin{aligned} \sum_{\mathcal{E} \subseteq [n]} \left(\prod_{i \in \mathcal{E}} \epsilon_i \right) \left(\prod_{i \in \mathcal{E}^c} (1 - \epsilon_i) \right) |\mathcal{E}| &= \sum_{\mathcal{E} \subseteq [n]} \left(\prod_{i \in \mathcal{E}} \epsilon_i \right) \left(\prod_{i \in \mathcal{E}^c} (1 - \epsilon_i) \right) \sum_{j=1}^n \mathbf{1}_{\mathcal{E}}(j) \\ &= \sum_{j=1}^n \sum_{\mathcal{E} \subseteq [n]} \left(\prod_{i \in \mathcal{E}} \epsilon_i \right) \left(\prod_{i \in \mathcal{E}^c} (1 - \epsilon_i) \right) \mathbf{1}_{\mathcal{E}}(j) \\ &= \sum_{j=1}^n \epsilon_j. \end{aligned}$$

For the dual code, we note that

$$\begin{aligned} H^\perp(\underline{X}|\underline{Y}(\underline{\epsilon})) &= \sum_{i=1}^n \epsilon_i - \sum_{\mathcal{E} \subseteq [n]} \left(\prod_{i \in \mathcal{E}} \epsilon_i \right) \left(\prod_{i \in \mathcal{E}^c} (1 - \epsilon_i) \right) \text{rank}(H_{\mathcal{E}}^\perp) && \text{(Definition of } H^\perp(\underline{X}|\underline{Y}(\underline{\epsilon}))) \\ &= \sum_{i=1}^n \epsilon_i - \sum_{\mathcal{E} \subseteq [n]} \left(\prod_{i \in \mathcal{E}} \epsilon_i \right) \left(\prod_{i \in \mathcal{E}^c} (1 - \epsilon_i) \right) \text{rank}(G_{\mathcal{E}}) && (H^\perp = G) \\ &= \sum_{i=1}^n \epsilon_i - \sum_{\mathcal{E} \subseteq [n]} \left(\prod_{i \in \mathcal{E}} \epsilon_i \right) \left(\prod_{i \in \mathcal{E}^c} (1 - \epsilon_i) \right) \text{rank}(G_{\mathcal{E}^c}) && (\mathcal{E}\text{-sum invariant: } \mathcal{E} \mapsto \mathcal{E}^c) \\ &= \left(\sum_{i=1}^n \epsilon_i \right) - k + H(\underline{X}|\underline{Y}(\underline{1} - \underline{\epsilon})). && \text{(Definition of } H(\underline{X}|\underline{Y}(\underline{1} - \underline{\epsilon}))) \end{aligned}$$

Taking the derivative with ϵ_i gives

$$\begin{aligned}
h_i^\perp(\underline{\epsilon}) &= \frac{d}{d\epsilon_i} H^\perp(\underline{X}|\underline{Y}(\underline{\epsilon})) \\
&= \frac{d}{d\epsilon_i} \left[\left(\sum_{i=1}^n \epsilon_i \right) - k + H(\underline{X}|\underline{Y}(\underline{1} - \underline{\epsilon})) \right] \\
&= 1 - \frac{d}{d\epsilon_i} H(\underline{X}|\underline{Y}(\underline{1} - \underline{\epsilon})) \\
&= 1 - h_i(\underline{1} - \underline{\epsilon}).
\end{aligned}$$

This completes the proof. \square

2.2 Random Codes

Let $\mathcal{C}^{(j)}$ be a sequence of random linear codes, each defined by a randomly chosen parity-check matrix $H^{(j)}$ of size $(n_j - k_j) \times n_j$, where $r \triangleq k_j/n_j$ is design rate of the sequence and $n_j \rightarrow \infty$. No assumptions are made about the distribution of $H^{(j)}$. Still, the true rate of the j -th code is given by $r(\mathcal{C}^{(j)}) = 1 - \frac{1}{n} \text{rank}(H^{(j)})$ and basic coding theory shows that $r(\mathcal{C}^{(j)}) \geq r$ with equality iff $H^{(j)}$ is full rank. Thus, we find that

$$r \leq r(\mathcal{C}^{(j)}).$$

Now, let $h^{(j)}(\epsilon)$ be the random EXIT function of the j -th random code and observe that

$$\begin{aligned}
r &\leq \limsup_{j \rightarrow \infty} \mathbb{E} \left[r(\mathcal{C}^{(j)}) \right] && (\mathbb{E} \text{ then } \lim \text{ sup}) \\
&= \limsup_{j \rightarrow \infty} \mathbb{E} \left[\int_0^1 h^{(j)}(\epsilon) d\epsilon \right] && (\text{EXIT Theorem}) \\
&= \limsup_{j \rightarrow \infty} \int_0^1 \underbrace{\mathbb{E} \left[h^{(j)}(\epsilon) \right]}_{\bar{h}^{(j)}(\epsilon)} d\epsilon && (\mathbb{E} \text{ over finite set}) \\
&\leq \int_0^1 \underbrace{\limsup_{j \rightarrow \infty} \bar{h}^{(j)}(\epsilon)}_{\bar{h}^{(\infty)}(\epsilon)} d\epsilon && (\text{Fatou's Lemma}) \\
&= \int_0^1 \bar{h}^{(\infty)}(\epsilon) d\epsilon.
\end{aligned}$$

2.3 BP EXIT Functions

Let $\mathcal{C}^{(j)}$ be a sequence of codes from the ensemble LDPC(λ, ρ), each defined by a randomly chosen parity-check matrix $H^{(j)}$ of size $(n_j - k_j) \times n_j$, where $r \triangleq k_j/n_j$ is design rate of the sequence and $n_j \rightarrow \infty$. Suppose the normalized bit and check degree distributions of each code in the sequence are given by $\lambda(x)$ and $\rho(x)$. In this case, one can use the BP estimate after ℓ_j iterations for each bit in the code. In the limit as $n_j \rightarrow \infty$ and $\ell_j \rightarrow \infty$, the erasure rate is concentrated around the density evolution estimate

$$h^{(BP)}(\epsilon) = L(x(\epsilon)),$$

where $x(\epsilon)$ is the limit of the decreasing sequence $x_{\ell+1} = \epsilon\lambda(1 - \rho(1 - x_\ell))$ starting from $x_0 = 1$.

Since $h^{(j)}(\epsilon)$ is the EXIT function associated with optimal APP detection of $\mathcal{C}^{(j)}$, it follows that the EXIT function associated with any other estimator cannot be smaller. Thus, one finds that

$$\bar{h}^{(\infty)}(\epsilon) \triangleq \limsup_{j \rightarrow \infty} \bar{h}^{(j)}(\epsilon) \leq h^{(BP)}(\epsilon).$$

Let us define the MAP noise threshold to be

$$\epsilon^{(MAP)} \triangleq \sup \left\{ \epsilon \in [0, 1] \mid \bar{h}^{(\infty)}(\epsilon) = 0 \right\}.$$

Then, one finds that

$$\int_0^1 \bar{h}^{(\infty)}(\epsilon) d\epsilon = \int_{\epsilon^{(MAP)}}^1 \bar{h}^{(\infty)}(\epsilon) d\epsilon \leq \int_{\epsilon^{(MAP)}}^1 \bar{h}^{(BP)}(\epsilon) d\epsilon.$$

This implies the following upper bound on the MAP noise threshold.

Theorem 6. *Let $\bar{\epsilon}$ be the largest value such that*

$$\int_{\bar{\epsilon}}^1 \bar{h}^{(BP)}(\epsilon) d\epsilon = r.$$

Then, $\epsilon^{(MAP)} \leq \bar{\epsilon}$.

Proof. If $\epsilon^{(MAP)} > \bar{\epsilon}$, then one gets the contradiction

$$\begin{aligned} r &\leq \int_0^1 \bar{h}^{(\infty)}(\epsilon) d\epsilon \\ &\leq \int_{\epsilon^{(MAP)}}^1 \bar{h}^{(\infty)}(\epsilon) d\epsilon \\ &\leq \int_{\epsilon^{(MAP)}}^1 \bar{h}^{(BP)}(\epsilon) d\epsilon \\ &\stackrel{(a)}{<} \int_{\bar{\epsilon}}^1 \bar{h}^{(BP)}(\epsilon) d\epsilon \\ &= r, \end{aligned}$$

where (a) follows from the fact that $\bar{h}^{(BP)}(\epsilon) \geq \bar{h}^{(\infty)}(\epsilon) > 0$ for $\epsilon \in (\bar{\epsilon}, \epsilon^{(MAP)})$. □

References

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