IMP: A Message-Passing Algorithm for Matrix Completion

Henry D. Pfister (joint with Byung-Hak Kim and Arvind Yedla)

Electrical and Computer Engineering Texas A&M University

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Outline

- Matrix Completion via Iterative Information Processing
- Factor Graph Model for Matrix Completion
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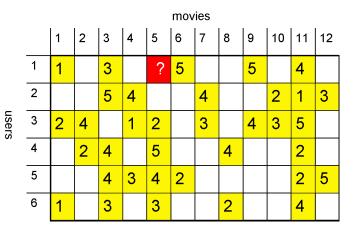
Matrix Completion Problem

"In its simplest form, the problem is to recover a matrix from a small sample of its entries,...

Imagine now that we only observe a few entries of a data matrix. Then is it possible to accurately—or even exactly—guess the entries that we have not seen?..."

- Candes and Plan '09

Motivation: The Netflix Challenge ('06-'09)



An overwhelming portion of the user-movie matrix (e.g., 99%) is unknown and the few observed movie ratings are noisy!

Recent Work on Matrix Completion

- Efficient Models and Practical Algorithms
 - Low rank matrix models and clustering models
 - Convex relaxation (SDP) and Bayesian approaches
- Exploration of the Fundamental Limits
 - Relationship between sparse observation and the recovery of missing entries
 - Cold-start problem in recommender systems

Main Differences

- Focus on the matrix where the entries (drawn from a finite alphabet) are modeled by a factor graph
- MP based algorithm to learn the missing information and eventually estimate missing entries

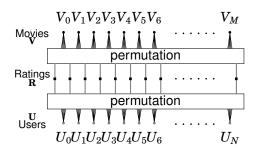


Our Goal: Matrix Completion via Iterative Processing

- Basic Approach
 - Establish a factor-graph model
 - Estimate parameters of model
 - Use for inference via message-passing (IMP)
- Benefits of our factor-graph model
 - Establishes a generative model for data matrices
 - Sparse observations reduce complexity
- Drawbacks of this approach
 - Mixes clustering and message-passing
 - Difficult to analyze behavior



Factor Graph Model (1): Conditional Independence



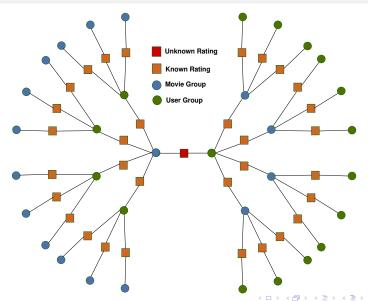
Assumption

The movie ratings R_{nm} (user n, movie m) are conditionally independent given the user group U_n and the movie group V_m

$$\Pr\left(\mathbf{R}_{O}|\mathbf{U},\mathbf{V}\right) \triangleq \prod_{(n,m)\in O} w\left(R_{nm}|U_{n},V_{m}\right)$$

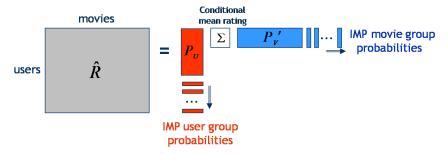
where $w(r|u,v) riangleq \Pr(R_{nm} = r|U_n = u, V_m = v)$

Factor Graph Model (2): Computational Tree



Factor Graph Model (3): Matrix Decomposition

MMSE estimates can be written as a matrix factorization



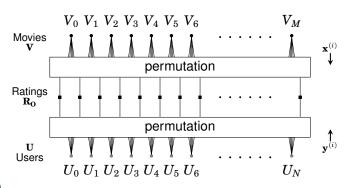
 In contrast to the standard low-rank matrix model, this adds non-negativity and normalization constraints

Inference by Message-Passing (IMP) Algorithm (1)

Step I. Initialize Group Rating Probabilities w(r|u,v)

- Cluster users (and movies) using variable-dimension vector quantization (VDVQ), which is a variant of VQ where the codebook vectors are full, but training vectors are sparse.
- Training is based on based on the generalized Lloyd algorithm (GLA) and the distance computed only on overlapping entries.
- For user clustering, the K codebook vectors can be thought of as K critics which have rated every movie.
- After clustering users/movies each into user/movie groups, estimate w(r|u,v) from the frequencies of each user-group / movie-group / rating triple.

IMP Algorithm (2)



Notation

Let $\mathbf{T}_{m \to n}^{(i)}$ be $m \to n$ computation tree after i iterations, then message from movie m to user n is $\mathbf{x}_{m \to n}^{(i)} \triangleq \Pr(V_m = v | \mathbf{T}_{m \to n}^{(i)})$ and message from user n to movie m is $\mathbf{y}_{n \to m}^{(i)} \triangleq \Pr(U_n = u | \mathbf{T}_{n \to m}^{(i)})$

IMP Algorithm (3)

Step II. Message-Passing Update of Group Vectors

Initialization of user/movie to prior group probabilities

$$\mathbf{x}_{m}^{(0)}(v)\!=\!p_{V}(v),\,\mathbf{y}_{n}^{(0)}(u)\!=\!p_{U}(u)$$

Recursive update for user/movie group probabilities

$$\begin{aligned} \mathbf{x}_{m \to n}^{(i+1)}(v) &\propto & \mathbf{x}_{m}^{(0)}(v) \prod_{k \in \mathcal{U}_{m} \setminus n} \sum_{u} w\left(r|u,v\right) \mathbf{y}_{k \to m}^{(i)}(u) \\ \mathbf{y}_{n \to m}^{(i+1)}(u) &\propto & \mathbf{y}_{n}^{(0)}(u) \prod_{k \in \mathcal{V}_{n} \setminus m} \sum_{v} w\left(r|u,v\right) \mathbf{x}_{k \to n}^{(i)}(v) \end{aligned}$$

 \mathcal{U}_m : all users who rated movie m \mathcal{V}_n : all movies whose rating by user n was observed

3 Update w(r|u,v) for group ratings



IMP Algorithm (4)

Step III. Approximate Matrix Completion

After *i* iterations of message-passing update,

ullet Output probability of rating R_{nm} given observed ratings

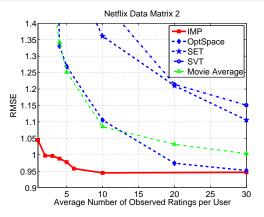
$$\hat{p}_{R_{nm}|\mathbf{R}_O}^{(i+1)}(r) \propto \sum_{u,v} \mathbf{x}_{m \rightarrow n}^{(i+1)}(v) w\left(r|u,v\right) \mathbf{y}_{n \rightarrow m}^{(i+1)}(u)$$

Minimize the mean-squared prediction error with

$$\hat{r}_{n,m}^{(i+1)} = \sum_{r \in \mathcal{R}} r \hat{p}_{R_{nm}|\mathbf{R}_O}^{(i+1)}(r)$$



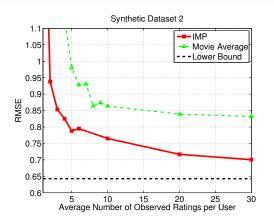
IMP Improves the Cold-Start Problem



Dataset Description

- Netflix submatrix of 5,035 movies and 5,017 users by avoiding movies and users with less than 3 ratings
- 16% of the users and 41% of the movies have less than 10 ratings

Generation of Synthetic Datasets



Dataset Description

 Synthetic Dataset generated after learning Netflix Data Matrix with 16 movie/user groups and randomly subsampled

Conclusion

Main Contributions

- Factor Graph Model: Probabilistic low-rank matrix model
- IMP Algorithm: Combines clustering with message-passing

Avenues for Future Research

- Combine with clustering via message-passing to get a fully iterative approach
- Obtain performance analysis of IMP algorithm via density evolution



Thank you